# LINEAR ELECTRIC ACTUATORS TYPE EL EL12, EL20, EL45, EL80, EL120, EL250 

## DESCRIPTION

Electric linear actuators EL series for modulating and open-close duty of control and process technology to operate control valves. The self-locking stem/stem nut is driven by an electric motor via a gearing. Load and limit switches define the stops for the end positions.

## MAIN FEATURES

- Valve protection against excessive force due to load-dependent seating.
- Comfortable manual operation when disengaging the actuator motor. - Mounting to valve made via yoke or mounting flange DIN 3358. The design enables easy connection to all types of valves. Standard version is suitable for Adcatrol valves.
- Generating a defined closing force in the end position leads to constantly tight shut-off of the valve.
- A robust metal cover protects efficiently against external contamination and manipulation.
- The actuators are in enclosure protection IP 65 (EL12 IP43) and are designed for rugged industrial use.
- Stall proof synchronous motors (or brake motors for higher positioning forces) ensure highest positioning accuracy.
- Mechanical stroke indication via anti-rotation bar.
- Exact, backlash-free measurement of actual valve stroke by direct coupling to the valve stem.
- Universally usable actuators due to control via 3-point-step controllers, analogue input signals ( $0 . . .10 \mathrm{~V}, 0$ (4)... 20 mA ), or fieldbus systems.
- Easy supplement to actuator with optional devices due to modular design.
- Limit switches, easily adjustable, for stroke limitation (not necessary for Adcatrol valves) or as signal for intermediate positions.
- Integrated, adjustable stroke setting to nominal stroke over the complete stroke range (without exchanging pinions, ...).
-Actuators with $230 \mathrm{~V}(50 \mathrm{~Hz})$ and $220 \mathrm{~V}(60 \mathrm{~Hz})$, have a tolerance of more or less 10\%.

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TECHNICAL DATA


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| Supply voltages ${ }^{\text {b }}$ | $24 \mathrm{~V} / 115 \mathrm{~V} / 230 \mathrm{~V} / 400 \mathrm{~V} 50 / 60 \mathrm{~Hz}, 24 \mathrm{~V}$ DC |
| :---: | :---: |
| Type of duty acc. to IEC 34-1 | S4-30\% c.d.f. $600 \mathrm{c} / \mathrm{h}$ |
| Cable entry | $2 \times \mathrm{M} 16 \times 1,5$ and 1 dummy plug M16 $\times 1,5$ |
| Electrical connection | Inside terminal board, terminal configuration according to electric connection wiring diagram |
| Switch off in end position | 2 load dependent switches, max. 250 V AC , rating for resistive load: max. 5 A , for inductive load: max. 3 A |
| Mounting position | As desired, except downward position |
| Ambient temperature | $-20{ }^{\circ} \mathrm{C}$ to $60{ }^{\circ} \mathrm{C}$ |
| Lubricant for gearing | Klüber Mickrolube GL 261 grease |
| Position indicator | by anti-rotation bar |
| Manual adjustment | side handwheel |
| Enclosure protection acc. to EN 60529 | IP65 |
| Trapezoidal thread | Tr $20 \times 3$ |
| Connection type | DIN 3210 G0 |
| Weight (kg) | 13,0 |

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| TECHNICAL DATA |  |  |
| :---: | :---: | :---: |
| TYPE | EL 250.1 | EL 250.2 |
| Positioning force (kN) | 25 |  |
| Positioning speed ${ }^{\text {a) }}$ (mm/min ; mm/s) | 25;0,4 | $50 ; 0,8$ |
| Power consumption - 230 V (W) | 157 | 218 |
| Nominal current - 230 V (A) | 0,73 | 1,0 |
| Type of motor ${ }^{\text {c }}$ | asyn |  |
| Motor protection ${ }^{\text {d }}$ | T |  |
| Max. stroke (mm) | 100 |  |
| Supply voltages ${ }^{\text {b) }}$ | $24 \mathrm{~V} / 115 \mathrm{~V} / 230 \mathrm{~V} / 400 \mathrm{~V} 50 / 60 \mathrm{~Hz}, 24 \mathrm{~V}$ DC |  |
| Type of duty acc. to IEC 34-1 | S4-30\% c.d.f. $600 \mathrm{c} / \mathrm{h}$ |  |
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| Mounting position | As desired, except downward position |  |
| Ambient temperature | $-20{ }^{\circ} \mathrm{C}$ to $60{ }^{\circ} \mathrm{C}$ |  |
| Lubricant for gearing | Klüber Mickrolube GL 261 grease |  |
| Position indicator | by anti-rotation bar |  |
| Manual adjustment | side handwheel |  |
| Enclosure protection acc. to EN 60529 | IP65 |  |
| Trapezoidal thread | Tr $26 \times 5$ |  |
| Connection type | DIN 3210 G0 |  |
| Weight (kg) | 19,0 |  |

a) At 60 Hz , the positioning speed and input power increase by $20 \%$.
b) Other supply voltages on request.
c) Syn - synchronous motor;

Asyn - asynchronous motor.
d) B - stallproof motor;

T - thermoswitch for temperature monitoring.

| ACCESSORIES AND OPTIONS |  |
| :---: | :---: |
| Accessories |  |
| Yoke for adaptation to valves. Refer to dimension sheet. | STALA / FLA |
| Mounting flange with central attachment Mxx. Refer to dimensions sheet (thrust rod must be secured against revolving). | ZFLA |
| Compact plug 10/24 poles with additional housing at actuator voltages $\leq 500 \mathrm{~V}$. | KS |
| Special finnish coating for use in the tropics ("tropics coating"). | LA-TR |
| Version IP65: with bellows at thrust rod and metal cover with seal (for EL12) | A-IP65 |
| Version with bellows at thrust rod (for EL20, 45, 80 and 120). | A-FAB |
| Options |  |
| Additional limit switches for signalling end positions or intermediate positions, freely adjustable, max. 250 V AC, rating for resistive load max. 5 A, for inductive load max. 3 A, max. 2 switches for EL20 and EL45, max. 4 switches for EL80 and EL120. | WE |
| Additional limit switches for signalling end positions or intermediate positions, freely adjustable, with gold-plated contacts for low voltage, max. 30 V AC, rating for resistive load max. 0.1 A , max. 2 switches for EL20 and EL45, max. 4 switches for EL80 and EL120. | WE-G |
| Potentiometer 100/130/200/500/1000/5000 Ohms or 10 kOhms Linearity error £ $0.5 \%$, max. 1.5 W , contact current 30 mA max. 2 pieces | POT |
| Electronic position feedback 2-/3-/4-wire system Inductive travel measuring, output 0 (4)... 20 mA Connection 24 V DC (not possible for EL12) | ESR |
| Positioning electronics for actuator control Input $0 \ldots 10 \mathrm{~V}, 0$ (4) ... 20 mA , output $0 \ldots 10 \mathrm{~V}, 0$ (4)... 20 mA Supply voltage $24,115,230 \mathrm{~V} 50 / 60 \mathrm{~Hz}$ | PEL |
| Heating resistor with thermoswitch against moisture with automatic temperature regulation, max. 15 Watts Supply voltage 24, 115, 230 V 50/60 Hz | HZMP |

ELECTRICAL CONNECTION

| 3 ~ asynchronous motor with brake and thermoswitch | $\begin{aligned} & 1 \sim \text { asynchronous } \\ & \text { motor } \\ & \text { with brake and } \\ & \text { thermoswitch } \\ & \hline \end{aligned}$ | Synchronous motor with thermoswitch | synchronous motor | Basic wiring diagram including optio |  |
| :---: | :---: | :---: | :---: | :---: | :---: |
|  |  |  |  |  |  |
|  |  |  | $\prod_{ \pm N}^{ \pm 1213}$ |  | Switch off in end postion via two load-dependant switches to control e.g. three-way mixing valves. |
|  |  |  | $\begin{aligned} & \oplus 1213 \\ & \pm N \end{aligned}$ |  | Switch off in end position via a load-dependent switch and a limit switch to control e.g. full-way valves without upper stop. Monitoring blocking in OPEN direction. |
|  |  |  |  |  | Control of three-phase actuators with thermoswitch. Switch off in end position via two loaddependant switches to control e.g. three-way mixing valves. <br> For motors without thermoswitch, the wiring to terminal 4 and 5 is not applicable. |
|  |  |  |  | 12] $1 3 1 1 4 1 1 5 \longdiv { 1 6 6 1 7 1 / 1 8 }$ <br> REG | Control of three-phase actuators with thermoswitch. Switch off in end position via a load-dependent switch and a limit switch to control e.g. full-way valves without upper stop. Monitoring blocking in OPEN direction. <br> For motors without thermoswitch, the wiring to terminal 4 and 5 is not applicable. |

WE Limit switch
HZ Heater with thermoswitch
POT Potentiometer
ESR Electronic position feedback
PEL Positioning electronics
WSE External reversing contactor unit
REG Process controller

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## DIMENSIONS

EL20 - EL45- EL80 - EL120


DIMENSIONS (mm)

| TYPE | EL20 - EL45 | EL80 - EL20 | EL250 | TYPE | EL20 - EL45 | EL80 - EL20 | EL250 |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| a | 94,5 | 130 | 190 | v |  |  |  |
| b | 173 | 197 | 226 | H | Actuators stroke (see technical data) |  |  |
| $\varnothing \mathrm{c}$ | 145 | 188 | 216 | 0 | 210 | 220 | 240 |
| d | 42 | 69 | 70 | p | 115 | 179 | 164 |
| $\varnothing$ e | 54 | 100 | 100 | $r$ | 45 | 45 | 51 |
| Ø f | 74 | 130 | 130 | $\varnothing$ w | 22 | 22 | 22 |
| $\varnothing \mathrm{g}$ | 3578 | 60 | 60 | M |  | M16 x 1,5 | M20 x 1,5 |
| i | 3 | 26 | 3 | max. G | M20 | M20 | M20 |
| k |  | 16 | 22 | Ø D | $\varnothing$ 40, $\varnothing 45$ | $\varnothing$ 40, $\varnothing 45$ | $\varnothing$ 45, $\varnothing 65$ |
| n | 14 | 20 | 26 | G | M10 | M10 | M16 |
| $\varnothing$ t | 50 | 102 | 102 | S | 110 (100) | 110 (100) | 125 |
| u | M6 | M10 | M10 | X | 190-228 |  | 235 |

## DIMENSIONS

## EL12



| TYPE | EL |
| :---: | :---: |
| $\varnothing \mathrm{D}$ | 40 |
| S | 100 |
| X 1 | 160 |
| X 2 | 55 |

## COMBINATION WITH A CONTROL VALVE

## (short instructions)

On delivery, the driving rod (1) is driven out to the bottom end limit (anti-rotation flange at bottom mark).
Further procedure:
-Insert valve stem (4) into the valve all the way to limit stop -Move the driving rod (1) up by rotating the hand wheel anti-clockwise by about 20 mm (see manual operation).
-Lift the actuator and yoke over the valve stem, place onto the top of the valve and secure using the mounting nut (9)
-Unscrew the locking plate (3) and the anti-rotation flange (8) in succession from the coupling flange (2) and allow it to fall over the stem.
-Remove the threaded socket (6) from the coupling flange and screw it onto the stem according to dimension L from table 1.
-Drive out the rod by rotating the handwheel clockwise until the threaded socket (6) stops in the coupling flange (2).
Screw the anti-rotation flange (8) and the locking plate (3) onto the coupling flange.
-Tighten the stem with the nut (5) against the threaded socket.

- When mounting pay attention that the valve plug is not pressed onto the seat and is not turned.
For electrical connections please report to IMI EL20.00



## MANUAL OPERATION

The manual adjustment must not be disengaged or engaged while the motor is running. Execute the manual adjustment only with motor being at standstill, hereto:
-With the left hand press the disengaging rod (11) with plate in direction of the outgoing driving rod toward the bottom -Simultaneously turn the handwheel (10) with the right hand until the coupling-in has sensible been executed -To actuate the linear actuator now turn the handwheel, hold the disengaging rod with the plate in engaged position Turning crank handle to the right (clockwise), the driving rod moves out of the actuator
Turning crank handle to the left (anti-clockwise), the driving rod moves into the actuator
(The linear actuator is automatically switched back to motoric operation, as soon as the disengaging rod will be released).

| (L) DIMENSIONS (mm) |  |  |  |  |  |  |  |  |  |  |  |  |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| VALVE TYPE | DN 15 | DN 20 | DN 25 | DN 32 | DN 40 | DN 50 | DN 65 | DN 80 | DN 100 | DN 125 | DN 150 | DN 200 |
| EV16G | 18 | 18 | 18 | 13 | 12 | 14 | 25 | 25 | 19 | - | - | - |
| EV40S | 18 | 18 | 18 | 13 | 12 | 14 | 25 | 25 | 19 | - | - | - |


| ACTUATOR SELECTION FOR TWO WAY VALVES TYPES EV16G, EV25G AND EV40S |  |  |  |  |  |  |  |  |  |  |  |  |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| ACTUATOR TYPE | DIFFERENTIAL PRESSURES (bar) |  |  |  |  |  |  |  |  |  |  |  |
|  | DN 15 | DN 20 | DN 25 | DN 32 | DN 40 | DN 50 | DN 65 | DN 80 | DN 100 | DN 125 | DN 150 | DN 200 |
| EL12 | 38 | 20 | 12 | 6,5 | 3,5 | 1,8 | - | - | - | - | - | - |
| EL20 | 40 | 40 | 28 | 16 | 9,9 | 5,8 | 3 | 1,7 | 0,6 | - | - | - |
| EL45 | 40 | 40 | 40 | 40 | 29,8 | 18,5 | 10,5 | 6,6 | 3,8 | - | - | - |
| EL80 | 40 | 40 | 40 | 40 | 40 | 36,4 | 21 | 13,6 | 8,2 | - | - | - |
| EL120 | - | - | - | - | 40 | 40 | 33,1 | 21,6 | 13,3 | 8,3 | 5,6 | 3 |
| EL250 | - | - | - | - | - | - | 40 | 40 | 30,2 | 19,1 | 12,1 | 5,5 |

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| ACTUATOR SELECTION FOR THREE WAY VALVES TYPES EV253G AND EV403S |  |  |  |  |  |  |  |  |  |  |  |  |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| ACTUATOR | DIFFERENTIAL PRESSURES (bar) |  |  |  |  |  |  |  |  |  |  |  |
| TYPE | DN 15 | DN 20 | DN 25 | DN 32 | DN 40 | DN 50 | DN 65 | DN 80 | DN 100 | DN 125 | DN 150 | DN 200 |
| EL12 | 25 | 22 | 13,2 | 7,1 | 3,8 | 1,9 | - | - | - | - | - | - |
| EL20 | 25 | 25 | 25 | 17,3 | 10,8 | 6,6 | 3,4 | 2 | 1,1 | - | - | - |
| EL45 | - | - | - | 25 | 25 | 19,8 | 11,6 | 7,3 | 3,8 | 2,4 | 1,5 | - |
| EL80 | - | - | - | - | 25 | 25 | 23,1 | 14,8 | 8,9 | 5,5 | 3,6 | - |
| EL120 | - | - | - | - | 25 | 25 | 25 | 23,1 | 14,5 | 9,1 | 6,1 | - |
| EL250 | - | - | - | - | - | - | - | - | - | - | - | - |


$\longrightarrow$ To be introduced on ".X.", if supplied in combination with the valve.

Example:
V25G valve model, EQP soft plug, PTFE/GR stem sealing, DN 50 , complete with 230 V electric actuator EL20 with positioner for $4-20 \mathrm{~mA}$ signal:

Code: EV.25G11L50.2013

REMARKS:
(1) - Omitted if the valve's size is already indicated in the code (to avoid redundancy).
(2) - Omitted if the standard valve is selected.


[^0]:    Remarks: V-rings stem packing

